

# Misanthrope process for large-scale simulation of pedestrian dynamics

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September 15, 2016 | Antoine Tordeux<sup>2</sup> | Forschungszentrum Jülich, Germany

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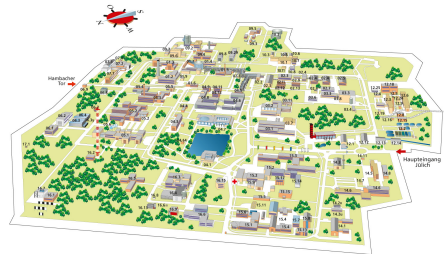
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# Forschungszentrum Jülich

## ◆ Multidisciplinary research center

- Health
- Energy
- Environment
- Information technology

## ◆ Approx. 5000 employees



## ◆ Jülich Supercomputing Centre – Division Civil Safety and Traffic

- Experimentation and modelling of pedestrian dynamics
- Fire and evacuation simulation
- Safety of large-scale events
- Collaboration with Wuppertal and Cologne Universities

# Motivations

- ◆ Nowadays more than **half of mankind lives in cities**
- ◆ **Dense crowds** are frequent in train stations, fairs, city centers or during large-scale events (sport, spectacle, concert, demonstration. . . )
- ◆ Knowledge of pedestrian dynamics is important for the design and optimization of facilities with respect to **safety or level of service**
- ◆ **Complex system**: experimentation, data collection, modelling and simulation of pedestrian dynamics are necessary

## Misanthrope process

- ◆ Borrowed from **Interacting Particle Systems** widely studied in theoretical physic<sup>3</sup> (see also zero-range, exclusion, or mean average processes)
- ◆ **Continuous time Markovian jump process** describing evolution of particles in a lattice
- ◆ **Unique stationary distribution** (finite set) that can easily be calculated by simulation (Monte Carlo experiments)
- ◆ **Misanthrope process** : Each site can contain several particles and the jump rate depends on particle numbers in departure and arrival sites<sup>4</sup>

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<sup>3</sup>T Liggett (1985) *Interacting particle systems* Springer

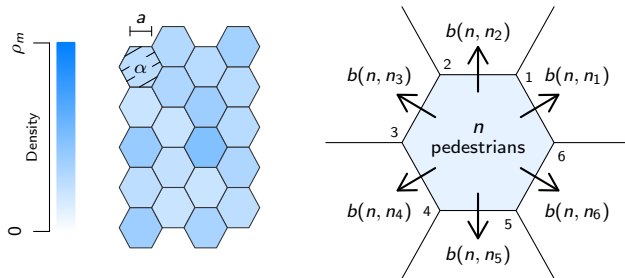
<sup>4</sup>C Coccozza-Thivent (1985) Z Wahr Verw Gebiete 70:509-523

## Pedestrian model

Hexagonal lattice with  $a > 0$  the face length (area  $\alpha = 1.5\sqrt{3}a^2$ )

Each hexagon can contain  $n \in [0, N]$  pedestrians,  $N \geq 1$

Jump rate  $b$  to define



## Model characteristics

**Discrete space / Continuous time** (also for the simulation)

**Intrinsically stochastic** (jump times exponentially distributed)

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→ **Mesoscopic approach** : Pedestrians are individually considered but their dynamics are aggregated by cell

→ **Exclusion model for  $N = 1$**  (size of the cell = size of a pedestrian)



## Jump rate function

♦ **The jump rate** of a pedestrian from a cell with  $n \geq 1$  pedestrian to cell  $i$  with  $n_i \geq 0$  pedestrians is

$$b_i(n, n_i) = \kappa \times J(n, n_i) \times D_i(J(n, n_i)) \quad (1)$$

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- ◆ The flow  $J(n, n_i)$  is the **minimum between the demand** of the considered cell and **the supply** of the destination cell  $i$ :

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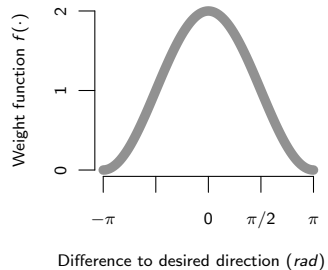
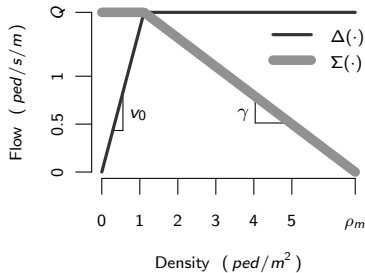
- ◆ The selected direction  $D_i(J(n, n_i))$  **maximizes the weighted flow to the desired direction  $h$** :

$$D_i(J(n, n_i)) = \begin{cases} 1 & \text{if } f(h - h_i)J(n, n_i) = \max_i f(h - h_i)J(n, n_i) \\ 0 & \text{otherwise} \end{cases} \quad (3)$$

# Model parameters

**Supply  $\Sigma(\cdot)$  and demand  $\Delta(\cdot)$  functions (fundamental diagram)**

**Weight  $f(\cdot)$  for the desired direction (here  $x \mapsto 1 + \cos(x)$ )**



## Simulation of the model

- ◆ Each cell with at least one pedestrian has an **exponential clock**

$$T_0 = t + \mathcal{E}(b) \quad (4)$$

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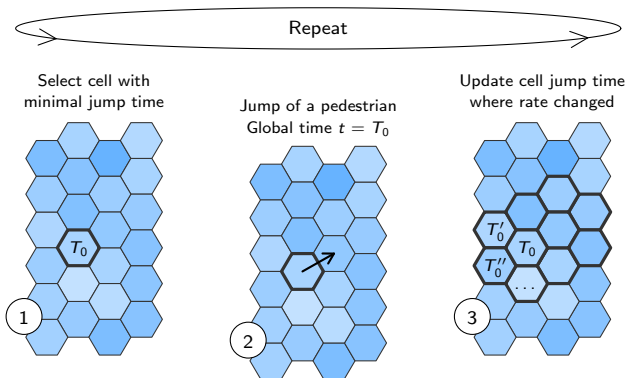
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- ◆ **Event-based simulation in continuous time** by taking successive minimum jump times :

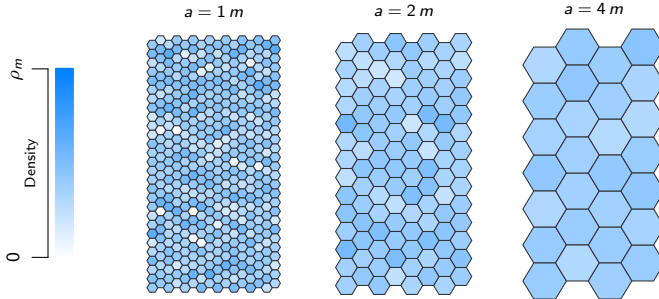
- Step 1.** Select the cell with minimal jump time
- Step 2.** Set time to selected cell jump time / Do the jump
- Step 3.** Update jump times of the cells where jump rate  $b$  changed
- Step 4.** Return to step 1

# Simulation of the model



# Simulation of uni-directional flows

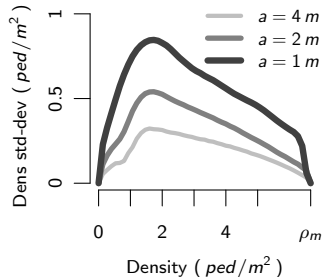
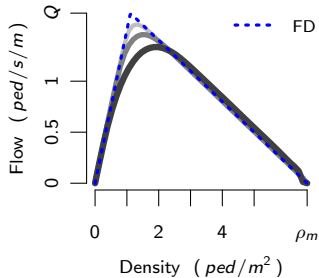
Snapshots in stationary state according to  $a$





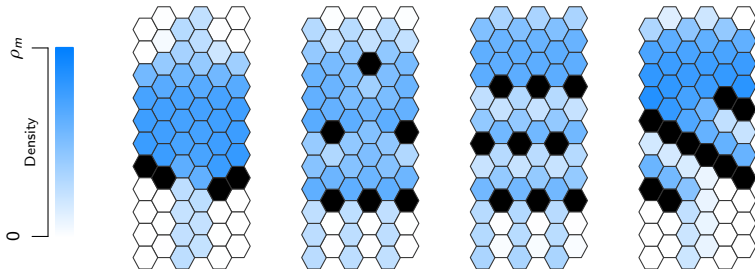
# Simulation of uni-directional flows

Fundamental diagram in stationary state according to  $a$



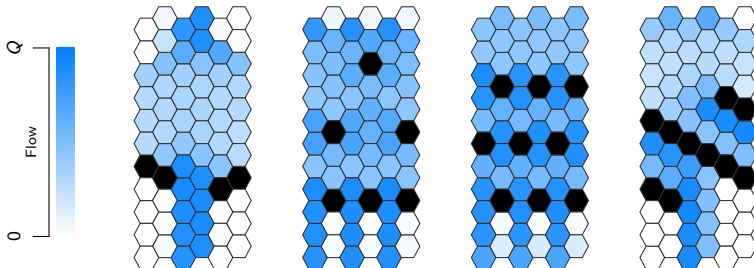
# Presence of obstacles

Mean performances in stationary state



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## Multi-directional flow model

◆  $d \in \mathbb{N}^*$  **possible desired directions**  $(h_1, h_2, \dots, h_d)$

→ System described by pedestrian numbers by direction  $(n^{h_1}, \dots, n^{h_d})$

**Proportion of pedestrians by direction**

$$p^h = \frac{n^h}{\sum_h n^h} \quad (5)$$

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◆ **Jump rate for the pedestrians with direction  $h$  to cell  $i$ :**

$$b_i^h(n, n_i) = p^h \times b_i(n, n_i) \quad (6)$$

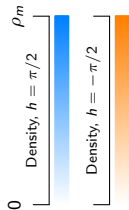
Proportion  $p^h$  of total flow affected to pedestrians with direction  $h$

Uni-directional model if only one direction exists ( $p^h = 1$ )

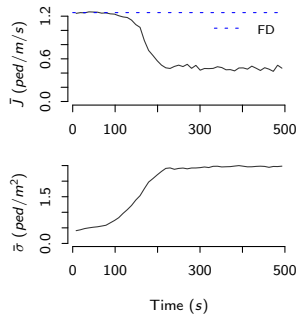
# Counter flows

Random initial condition

$$\rho = 2.5 \text{ ped/m}^2 \quad a = 2.5 \text{ m}$$



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## Multi-directional flow model (2)

- ◆ **Total flow bounded** by the proportion by direction to model **frictions for pedestrians with different directions**

$$J(n, n_i) \rightarrow J^h(n, n_i) = \min\{\tilde{p}_i^h Q, J(n, n_i)\} \quad (7)$$

with  $\tilde{p}^h = p_0 + (1 - p_0)p^h$  and new parameter  $p_0 \in [0, 1]$

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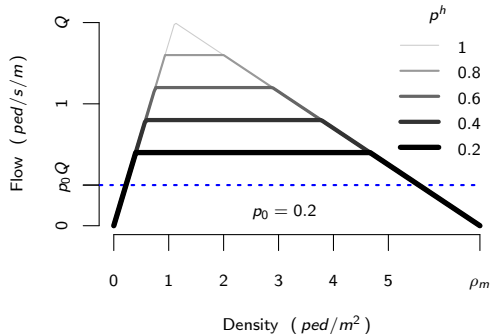
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Same model as previous one if  $p_0 = 1$  ( $J^h = J$  for all  $h$ )

If  $p_0 = 0$ , then  $\tilde{p}^h = p^h$ : the jump rates to cells that do not contain any pedestrian with the same direction are nil



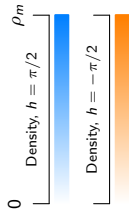
# Bounded fundamental diagram



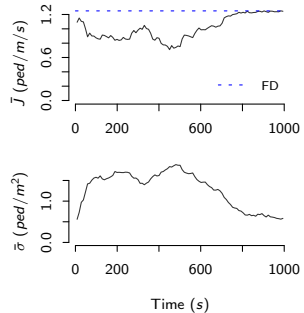
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Random initial condition

$$p_0 = 0.2 \quad \rho = 2.5 \text{ ped}/\text{m}^2 \quad a = 2.5 \text{ m}$$



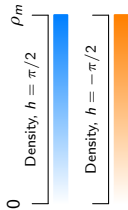
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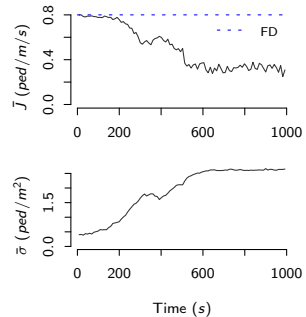
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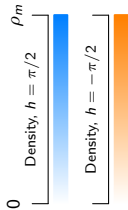
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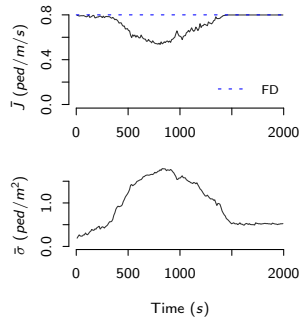
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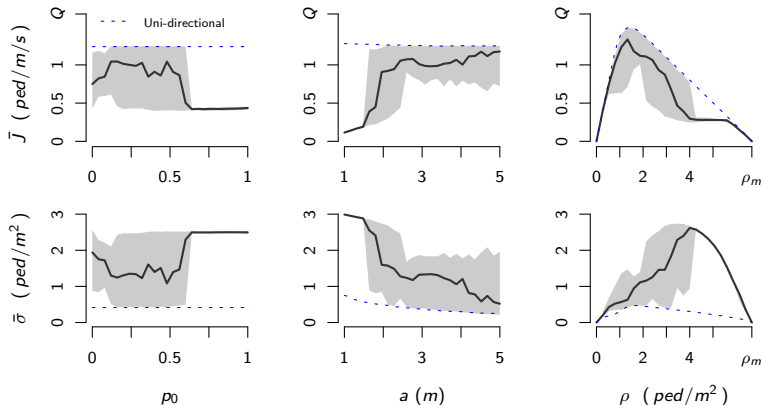
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Performances in stationary state<sup>5</sup>

$p_0 = 0.2$

$\rho = 2.5 \text{ ped/m}^2$

$a = 2.5 \text{ m}$



<sup>5</sup>50 experiments per parameter value; Line: mean value; Grey area: Min-max interval

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Description of **realistic fundamental diagrams, congestion/rarefaction** and **lane formation** for large cells (i.e. low variability – *Freezing by Heating effect*)

## Working perspectives

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- ◆ **Model to understand  $\rightsquigarrow$  Model to predict**
  - Technical and strategic planning motion modelling + other mechanisms
  - Large-scale simulation of pedestrian dynamics